Aims and Scope

The interdisciplinary journal publishes original and new results on recent developments, discoveries and progresses on Discontinuity, Nonlinearity and Complexity in physical and social sciences. The aim of the journal is to stimulate more research interest for exploration of discontinuity, complexity, nonlinearity and chaos in complex systems. The manuscripts in dynamical systems with nonlinearity and chaos are solicited, which includes mathematical theories and methods, physical principles and laws, and computational techniques. The journal provides a place to researchers for the rapid exchange of ideas and techniques in discontinuity, complexity, nonlinearity and chaos in physical and social sciences. Topics of interest include but not limited to:

- Complex and hybrid dynamical systems
- Discontinuous dynamical systems (i.e., impulsive, time-delay, flow barriers)
- Nonlinear discrete systems and symbolic dynamics
- Fractional dynamical systems and control
- Stochastic dynamical systems and randomness
- Complexity, self-similarity and synchronization
- Complex nonlinear phenomena in physical systems
- Stability, bifurcation and chaos in complex systems
- Turbulence and other complex phenomena in hydrodynamics
- Nonlinear waves and solitons
- Dynamical networks
- Combinatorial aspects of dynamical systems
- Biological dynamics and biophysics
- Pattern formation, social science and complexization

No length limitations for contributions are set, but only concisely written manuscripts are published. Brief papers are published on the basis of Technical Notes. Discussions of previous published papers are welcome.

Peer Review

*Discontinuity, Nonlinearity, and Complexity* adopts the traditional blind-review policy in which the reviewers’ names are concealed for submission author(s) for free submission. Each submitted manuscript is reviewed at least two referees in appropriate fields. In addition, the editorial board members’ recommendation or established experts’ recommendation publication are welcome.

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